Taylor's Theorem Taylor polynomials and Lagrange error bounds

Edward Pearce

The University of Sheffield

Wednesday 16th December

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Taylor polynomial

Taylor's Theorem

Historical note



Brook Taylor (1685-1731)



Direct and Reverse Methods of Incrementation $(1715)_{12}$, 2

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Taylor's Theorem

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Motivation

Question How do we know $e \approx 2.71828...?$



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Question

How do we know $e \approx 2.71828...$? How might we calculate the value to greater precision?

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Motivation

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How do we know $e \approx 2.71828...$? How might we calculate the value to greater precision? How could computers help?

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More general question

How can we effectively approximate transcendental functions?

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How can we effectively approximate *transcendental* functions? e.g. $\exp(x)$, $\sin(x)$, $\cos(x)$, $\tan(x)$, $\log(x)$, ...

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Idea

Polynomials are easy to compute, take derivatives, integrate...

Question

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More general question

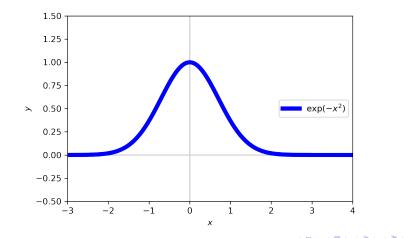
How can we effectively approximate *transcendental* functions? e.g. $\exp(x)$, $\sin(x)$, $\cos(x)$, $\tan(x)$, $\log(x)$, ...

Idea

Polynomials are easy to compute, take derivatives, integrate... We can approximate a k-times differentiable function around a given point by a polynomial of degree k.

Applications

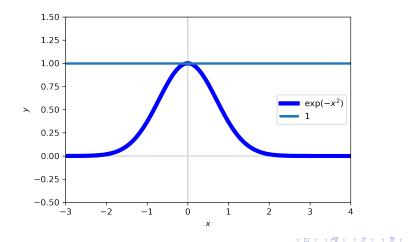
Example: Density of Normal Distribution



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Linear approximation to bell curve

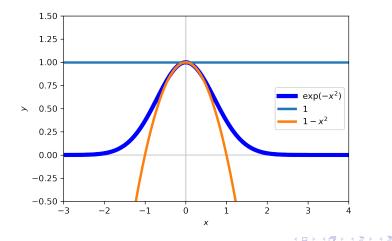


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Applications

Quadratic approximation to bell curve

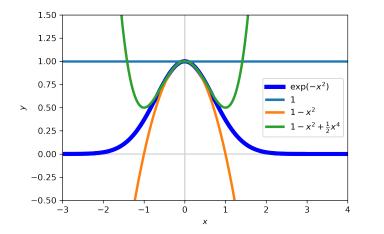


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Applications 000000

Polynomial approximations to bell curve



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Taylor polynomial

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We can approximate a k-times differentiable function around a given point by a polynomial of degree k.



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We can approximate a k-times differentiable function around a given point by a polynomial of degree k. What is the 'best' degree k polynomial we can choose?

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Taylor polynomial

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Definition

Let $k \ge 1$ be an integer and let $f : \mathbb{R} \to \mathbb{R}$ be a k times differentiable at the point $a \in \mathbb{R}$. Define the k-th Taylor polynomial of the function f at the point a to be

$${\sf P}_k(x)=f(a){+}f'(a)(x{-}a){+}rac{f''(a)}{2!}(x{-}a)^2{+}{\dots}{+}rac{f^{(k)}(a)}{k!}(x{-}a)^k$$

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$$P_k(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \ldots + \frac{f^{(k)}(a)}{k!}(x-a)^k$$

Remark

The k-th Taylor polynomial $P_k(x)$ of the function f at the point a is defined such that $P_k^{(j)}(a) = f^{(j)}(a)$ for all integers $0 \le j \le k$.

Special cases 1

Example (Linear approximation) Near x = a, $f(x) \approx f(a) + f'(a)(x - a)$



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Taylor's Theorem

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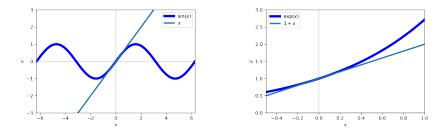
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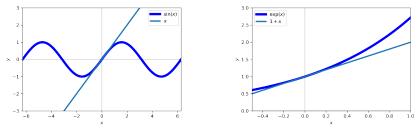
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The graph of $y = P_1(x)$, approximating the function f near a, is the tangent line to the graph y = f(x) at x = a.

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Special cases 2

Example (Quadratic approximation)

Sufficiently close to x = a, a more accurate approximation is $f(x) \approx P_2(x) = f(a) + f'(a)(x - a) + \frac{f''(a)}{2!}(x - a)^2$



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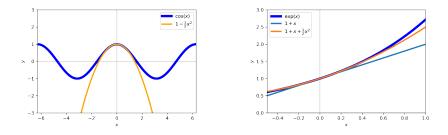
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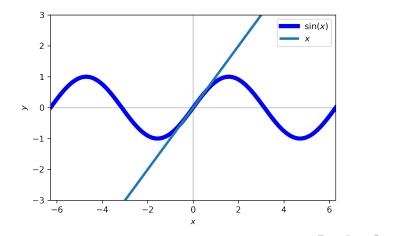


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Applications

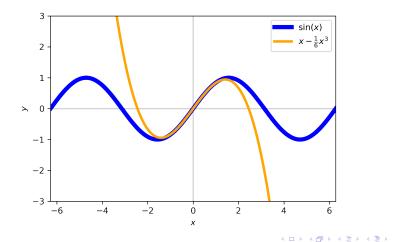
More terms/higher order approximations, ...



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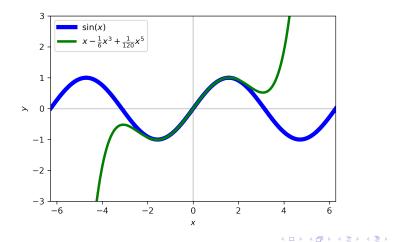
More terms, more accuracy, ...



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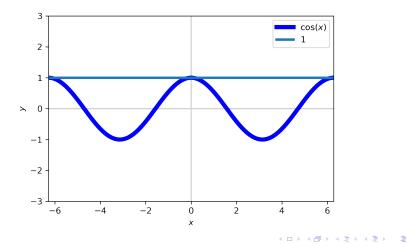
How accurate, how fast?



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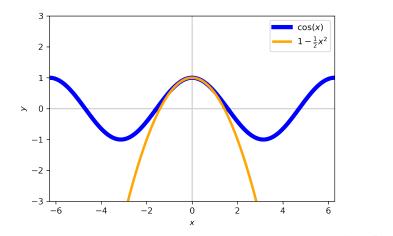
How many terms to bound error (decimal places)?



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Max error for given interval and polynomial degree?

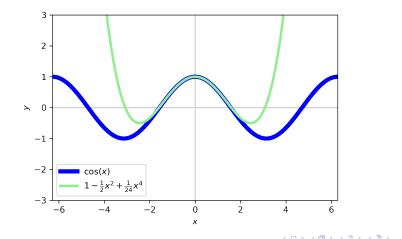


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Applications

Size of interval with given error tolerance?



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Theorem (Taylor's theorem)

Let $f : \mathbb{R} \to \mathbb{R}$ be a k times differentiable at the point $a \in \mathbb{R}$, and let $P_k(x)$ be the k-th Taylor polynomial of f at a. Then the error/remainder $R_k(x) = f(x) - P_k(x)$ between the function f and its k-th Taylor polynomial can be expressed in the form:

$$R_k(x) = h_k(x)(x-a)^k$$

for a function $h_k : \mathbb{R} \to \mathbb{R}$ such that $\lim_{x \to a} h_k(x) = 0$.

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Interpretation

As $x \to a$, the error term $R_k(x) = f(x) - P_k(x)$ tends to 0 faster than $(x - a)^k$, the highest order term of $P_k(x)$, so $P_k(x)$ is the "asymptotic best fit" degree k polynomial to f_k at $a_k \ge \infty$

Lagrange form for Taylor approximation error

Theorem (Mean-value form of the remainder) Let $f : \mathbb{R} \to \mathbb{R}$ be a k + 1 times differentiable on (a, x) with $f^{(k)}$ continuous on [a, x]. Then the error/remainder $R_k(x) = f(x) - P_k(x)$ can be expressed as:

$${R_k}(x) = rac{{{f^{\left({k + 1}
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for some real number $c \in (a, x)$. Similarly, when x < a.

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Applications

Theorem (Mean Value Theorem (MVT))

Let $f : [a, b] \to \mathbb{R}$ be a continuous function on the closed interval [a, b] and differentiable on the open interval (a, b), where a < b. Then there exists some $c \in (a, b)$ such that

$$f'(c) = rac{f(b) - f(a)}{b - a}$$

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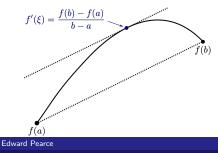
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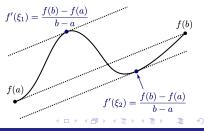
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Proof of Taylor's theorem (explicit remainder) For fixed *a* and *x*, consider the function $F(t) : [a, x] \to \mathbb{R}$ constructed such that F(x) = f(x) and $F(a) = P_k(x)$ given by

$$F(t) = f(t) + f'(t)(x-t) + \frac{f''(t)}{2!}(x-t)^2 + \ldots + \frac{f^{(k)}(t)}{k!}(x-t)^k$$

which also satisfies the criteria for MVT by the assumptions on f. Note that $F(x) - F(a) = f(x) - P_k(x) = R_k(x)$.

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which also satisfies the criteria for MVT by the assumptions on f. Note that $F(x) - F(a) = f(x) - P_k(x) = R_k(x)$. We compute the derivate of F with respect to t using the product rule and chain rule, and note a telescoping cancellation of terms such that

$$F'(t) = rac{f^{(k+1)}(t)}{k!}(x-t)^k$$

Proof of Taylor's theorem (part 2)

Now consider the function $H(t) : [a, x] \to \mathbb{R}$ given by

$$H(t) = F(t) + \frac{F(x) - F(a)}{(x - a)^{k+1}} (x - t)^{k+1}$$

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Proof of Taylor's theorem (part 2)

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which also satisfies the criteria for MVT, with H(x) = H(a). Applying the MVT (Rolle's theorem) to H(t), there exists $c \in (a, x)$ such that

$$H'(c) = rac{f^{(k+1)}(c)}{k!}(x-c)^k - (k+1)rac{R_k(x)}{(x-a)^{k+1}}(x-c)^k = 0$$

Rearranging this gives the desired formula for $R_k(x)$.

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Remarks on the proof

Throughout the previous proof, we were treating a and x as fixed constants and instead using t as the independent variable when applying the Mean Value Theorem.



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Throughout the previous proof, we were treating a and x as fixed constants and instead using t as the independent variable when applying the Mean Value Theorem.

If we decided to apply the MVT directly to F rather than to H we would have obtained an alternative formula for the Taylor approximation error (called the Cauchy form):

$$R_k(x) = rac{f^{(k+1)}(c)}{k!}(x-c)^k(x-a)$$

for some real number $c \in (a, x)$ (a different constant than in the Lagrange form of the remainder).

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Applications

Question

How many terms in a Taylor polynomial approximation do we need to bound the error to a certain number of decimal places?



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Applications

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How many terms in a Taylor polynomial approximation do we need to bound the error to a certain number of decimal places?

Theorem (Estimating Taylor approximation error) Suppose f is (k + 1) times continuously differentiable on [a - r, a + r] and $|f^{(k+1)}(x)| \le M$ for all $x \in (a - r, a + r)$ (some r > 0). Then we can bound the error

$$|R_k(x)| = \frac{|f^{(k+1)}(c)|}{(k+1)!} |x-a|^{k+1} \le M \frac{|x-a|^{k+1}}{(k+1)!} \le M \frac{r^{k+1}}{(k+1)!}$$

for all $x \in (a - r, a + r)$.

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Examples

For
$$x \in (-\frac{\pi}{4}, \frac{\pi}{4})$$
, $|\cos(x) - (1 - \frac{1}{2}x^2)| < \frac{\pi^4}{24 \times 4^4} \approx 0.016$..



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For $x \in (-\frac{\pi}{2}, \frac{\pi}{2})$, $|\cos(x) - (1 - \frac{1}{2}x^2 + \frac{1}{24}x^4)| < \frac{\pi^6}{720 \times 2^6} \approx 0.02$

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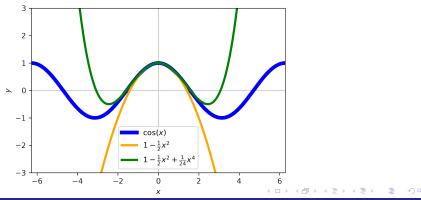
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Taylor's Theorem

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Motivation 00000 Taylor's Theorem

Applications

We may calculate $e \approx 2.71828$, correct up to five decimal places, using the fact that for $-1 \le x \le 1$

$$e^{x} = 1 + x + rac{x^{2}}{2!} + \ldots + rac{x^{9}}{9!} + R_{9}(x), \quad |R_{9}(x)| < 10^{-5}$$

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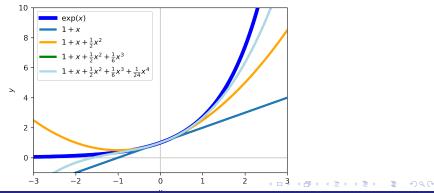
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 Motivation
 Taylor polynomial
 Taylor's Theorem

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Applications

Summary

Key Takeaway

Taylor polynomials and Taylor series translate derivative information at a single point into approximation information around that point.



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- We can approximate differentiable functions by polynomials
- We can calculate an upper bound on the error between our approximations to a function and its true value

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Key Takeaway

Taylor polynomials and Taylor series translate derivative information at a single point into approximation information around that point.

- We can approximate differentiable functions by polynomials
- We can calculate an upper bound on the error between our approximations to a function and its true value
- We understand that linear and quadratic approximations have practical uses in physics and engineering, but may diverge outside a neighbourhood of the approximation point

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Future Directions

 Examples of functions where Taylor's theorem does not apply (e.g. antiderivative of sin(¹/_x))

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Future Directions

- Examples of functions where Taylor's theorem does not apply (e.g. antiderivative of sin(¹/_x))
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- Applications in numerical analysis (finite difference methods)

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Taylor's Theorem



Thanks for listening!

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